

$$a^{l-1} \xrightarrow{W^l} z^l \xrightarrow{f_l} a^l \xrightarrow{W^{l+1}} z^{l+1} \xrightarrow{f_{l+1}} a^{l+1} \quad y$$

$n \times 1 \quad n \times m \quad n \times 1 \quad n \times 1 \quad p \times n \quad p \times 1 \quad p \times 1 \quad p \times 1 \quad p \times 1$

$$z^l = W^l a^{l-1} + b^l$$

$$a^{l+1} = f_l(z^l)$$

$$\text{vec}(AXB) = (B^T \otimes A) \text{vec}(X)$$

$$A(m \times n) \quad B(p \times q) \quad A \otimes B = [A_{ij} B]_{mp \times nq}$$

设已知: ① $\nabla_{z^l}^2 J = Q^l \in \mathbb{R}^{n \times n}$

$$\therefore \text{vec}(d \nabla_{z^l} J) = Q^{lT} \text{vec}(dz^l)$$

$$\vec{r} \text{vec}(dz^l) = (\nabla_{W^l} z^l)^T \text{vec}(dW^l)$$

$$\therefore \text{vec}(d \nabla_{z^l} J) = Q^{lT} (\nabla_{W^l} z^l)^T \text{vec}(dW^l) \quad \dots \dots \textcircled{1}$$

② $\nabla_{W^l}^2 z^l = P^l \in \mathbb{R}^{mn \times mn^2}$

$$\therefore \text{vec}(d \nabla_{W^l} z^l) = P^{lT} \text{vec}(dW^l) \quad \dots \dots \textcircled{2}$$

$$\therefore \text{vec}(dJ) = \underbrace{(\nabla_{z^l} J)}_{n \times 1}^T \text{vec}(dz^l)$$

$$\vec{r} \text{vec}(dz^l) = (\nabla_{W^l} z^l)^T \text{vec}(dW^l)$$

$$\therefore \text{vec}(dJ) = (\nabla_{z^l} J)^T (\nabla_{W^l} z^l)^T \text{vec}(dW^l)$$

$$\text{则} \quad \nabla_{W^l} J = \underbrace{\nabla_{W^l} z^l}_{mn \times n} \cdot \underbrace{\nabla_{z^l} J}_{n \times 1}$$

$$\therefore d \nabla_{W^l} J = d(\nabla_{W^l} z^l) \cdot \nabla_{z^l} J + \nabla_{W^l} z^l \cdot d(\nabla_{z^l} J)$$

$$\begin{aligned} \therefore \text{vec}(d \nabla_{W^l} J) &= \text{vec} \left(\underbrace{I_{mn}}_{m \times m} \cdot \underbrace{d \nabla_{W^l} z^l}_{mn \times n} \cdot \underbrace{\nabla_{z^l} J}_{n \times 1} \right) + \text{vec} \left(\underbrace{\nabla_{W^l} z^l}_{mn \times n} \cdot \underbrace{d \nabla_{z^l} J}_{n \times 1} \cdot \underbrace{I_1}_{1 \times 1} \right) \\ &= \left(\underbrace{(\nabla_{z^l} J)^T}_{1 \times n} \otimes \underbrace{I_{mn}}_{m \times m} \right) \underbrace{\text{vec}(d \nabla_{W^l} z^l)}_{mn^2 \times 1} + \underbrace{\nabla_{W^l} z^l}_{m \times n} \text{vec}(d \nabla_{z^l} J)_{n \times 1} \end{aligned}$$

将 \otimes 变 $\otimes X$ \rightarrow $\left((\nabla_{z^l} J)^T \otimes I_{mn} \right) P^{lT} \text{vec}(dW^l) + (\nabla_{W^l} z^l) \cdot Q^{lT} \cdot (\nabla_{W^l} z^l)^T \text{vec}(dW^l)$

$$\therefore \nabla_{W^l}^2 J = \underbrace{P^l}_{m \times mn^2} \cdot \underbrace{(\nabla_{z^l} J \otimes I_{mn})}_{n \times mn} + \underbrace{(\nabla_{W^l} z^l)}_{m \times n} \underbrace{Q^l}_{n \times n} \underbrace{(\nabla_{W^l} z^l)^T}_{n \times mn}$$

$$\nabla_{b^l} J = \nabla_{b^l} z^l \cdot \nabla_{z^l} J$$

$n \times 1 \quad \quad n \times n \quad \quad n \times 1$

$$\therefore d\nabla_{b^l} J = d\nabla_{b^l} z^l \cdot \nabla_{z^l} J + \nabla_{b^l} z^l \cdot d\nabla_{z^l} J$$

$$\begin{aligned} \therefore \text{vec}(d\nabla_{b^l} J) &= \text{vec}(I_n \cdot d\nabla_{b^l} z^l \cdot \nabla_{z^l} J) + \text{vec}(\nabla_{b^l} z^l \cdot d\nabla_{z^l} J \cdot I_1) \\ &= \underbrace{((\nabla_{z^l} J)^T \otimes I_n)}_{=0} \text{vec}(d\nabla_{b^l} z^l) + \nabla_{b^l} z^l \cdot \text{vec}(d\nabla_{z^l} J) \end{aligned}$$

$n \times n \quad n \times n \quad n \times 1 \quad \quad n \times n \quad n \times 1 \quad 1 \times 1$

$$\text{类 } \textcircled{1} \text{ 为 } \nabla_{b^l} z^l \cdot Q^{lT} (\nabla_{b^l} z^l)^T \text{vec}(db^l)$$

$$\therefore \nabla_{b^l}^2 J = (\nabla_{b^l} z^l) Q^l (\nabla_{b^l} z^l)^T$$

$n \times n \quad \quad n \times n \quad n \times n \quad \quad n \times n$

$$z^l = W^l a^{l-1} + b^l$$

$$\therefore dz^l = dW^l \cdot a^{l-1}$$

$$\therefore \text{vec}(dz^l) = \text{vec}(I_n \cdot dW^l \cdot a^{l-1})$$

$$= (a^{l-1})^T \otimes I_n \text{vec}(dW^l)$$

$$\therefore \nabla_{W^l} z^l = a^{l-1} \otimes I_n \in \mathbb{R}^{n \times n}$$

$m \times 1 \quad \quad n \times n$

$$\therefore dz^l = db^l$$

$$\therefore \text{vec}(dz^l) = \text{vec}(db^l)$$

$$\therefore \nabla_{b^l} z^l = I_n \in \mathbb{R}^{n \times n}$$

$$\vec{z}^{l+1} = \frac{1}{n} \sum_{i=1}^n \vec{z}_i - \vec{z}$$

$$\nabla_{\vec{z}^{l+1}}^2 J = Q^{l+1}$$

$$\nabla_{\vec{z}^{l+1}} J = \delta^{l+1}$$

$$J = -y^T \ln a^{l+1} - (1-y)^T \ln (1-a^{l+1})$$

$$\leftarrow d\sigma(x) = \sigma'(x) \odot dx$$

$$dJ = (-y + a^{l+1})^T dz^{l+1}$$

$$\therefore \text{vec}(dJ) = \text{vec} \left(\begin{matrix} (-y + a^{l+1})^T & dz^{l+1} \\ \hline \cdot & \cdot \end{matrix} \cdot I_1 \right)$$

$1 \times 1 \qquad \qquad \qquad 1 \times p \qquad \qquad p \times 1 \qquad 1 \times 1$

$$= (-y + a^{l+1})^T \text{vec}(dz^{l+1})$$

$$\therefore \nabla_{\vec{z}^{l+1}} J = \delta^{l+1} = -y + a^{l+1}$$

$$d(\nabla_{\vec{z}^{l+1}} J) = d(-y + a^{l+1}) = da^{l+1}$$

$$\leftarrow \because a^{l+1} = \text{sigmoid}(z^{l+1}) \quad \vec{a}^{l+1} = s(z^{l+1})$$

$$s' = s(1-s)$$

$$= \text{diag}(a^{l+1} \odot (1-a^{l+1})) dz^{l+1}$$

$$\therefore \text{vec}(d\nabla_{\vec{z}^{l+1}} J) = \text{vec} \left(\text{diag}(a^{l+1} \odot (1-a^{l+1})) \cdot dz^{l+1} \cdot I_1 \right)$$

$$= \text{diag}(a^{l+1} \odot (1-a^{l+1})) \cdot \text{vec}(dz^{l+1})$$

$$\therefore \nabla_{\vec{z}^{l+1}}^2 J = Q^{l+1} = \text{diag}(a^{l+1} \odot (1-a^{l+1})) = \text{diag}(a^{l+1}) - a^{l+1} \cdot a^{(l+1)T}$$

$P \times P \qquad \qquad P \times P$

$$= \begin{pmatrix} a_1^{l+1}(1-a_1^{l+1}) & & & \\ & a_2^{l+1}(1-a_2^{l+1}) & & \\ & & \ddots & \\ & & & a_p^{l+1}(1-a_p^{l+1}) \end{pmatrix}_{p \times p}$$

$$\nabla_{z^{l+1}} J = Q^{l+1} \delta^{l+1}, \quad \text{求 } Q^l = \nabla_{z^l} J$$

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设已知 $\nabla_{z^{l+1}} J = \delta^{l+1}$

$$\therefore \text{vec}(dJ) = \delta^{(l+1)T} \text{vec}(dz^{l+1}) \dots \dots \dots \textcircled{3}$$

$$\text{又 } z^{l+1} = W^{l+1} a^l + b^{l+1}$$

$$\therefore dz^{l+1} = W^{l+1} da^l \quad \text{又 } a^l = f_l(z^l) \quad \therefore da^l = \text{diag}(f'_l(z^l)) \cdot dz^l$$

$$\therefore dz^{l+1} = W^{l+1} \text{diag}(f'_l(z^l)) dz^l \dots \dots \dots \textcircled{4}$$

$$\textcircled{4} \wedge \textcircled{3} \quad \text{vec}(dJ) = \delta^{(l+1)T} \text{vec}(W^{l+1} \text{diag}(f'_l(z^l)) \cdot dz^l \cdot I_1)$$

$$= \delta^{(l+1)T} W^{l+1} \text{diag}(f'_l(z^l)) \cdot \text{vec}(dz^l)$$

$$\therefore \nabla_{z^l} J = \delta^l = \text{diag}(f'_l(z^l)) W^{(l+1)T} \delta^{l+1}$$

$$\text{即 } \nabla_{z^l} J = \text{diag}(f'_l(z^l)) \cdot W^{(l+1)T} \cdot \nabla_{z^{l+1}} J$$

$$\therefore \text{vec}(d\nabla_{z^l} J) = \text{vec}(d \text{diag}(f'_l(z^l)) \cdot W^{(l+1)T} \cdot \nabla_{z^{l+1}} J) \leftarrow \because f_l(\cdot) \text{ 若是 ReLU 这种 piecewise lin. } f_l'' = 0.$$

$$+ \text{vec}(\underbrace{\text{diag}(f'_l(z^l)) \cdot W^{(l+1)T}}_A \cdot \underbrace{d\nabla_{z^{l+1}} J}_X \cdot \underbrace{I_1}_B)$$

$$= \text{diag}(f'_l(z^l)) \cdot W^{(l+1)T} \cdot \text{vec}(d\nabla_{z^{l+1}} J)$$

$$= \text{diag}(f'_l(z^l)) \cdot W^{(l+1)T} \cdot Q^{(l+1)T} \text{vec}(dz^{l+1})$$

$$\text{代 } \lambda \textcircled{4} \quad = \text{diag}(f'_l(z^l)) \cdot W^{(l+1)T} \cdot Q^{(l+1)T} \cdot \text{vec}(W^{l+1} \text{diag}(f'_l(z^l)) dz^l \cdot I_1)$$

$$= \text{diag}(f'_l(z^l)) \cdot W^{(l+1)T} \cdot Q^{(l+1)T} W^{l+1} \cdot \text{diag}(f'_l(z^l)) \cdot \text{vec}(dz^l)$$

$$= Q^{lT} \text{vec}(dz^l)$$

$$\therefore Q^l = \underbrace{\text{diag}(f'_l(z^l))}_{n \times n} \cdot \underbrace{W^{(l+1)T}}_{n \times p} \cdot \underbrace{Q^{l+1}}_{p \times p} \cdot \underbrace{W^{l+1}}_{p \times n} \cdot \underbrace{\text{diag}(f'_l(z^l))}_{n \times n}$$